

August 21, 2026 | SAFL AI Futures Dialogue

Beyond the Lab: User-Aligned Assessment of Taskable AI Systems

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01

Introduction

02

Foundational
Approach

03

Generalizations

04

Future Work

Taskable AI Systems: Systems that can Learn and Plan



User gives a task and Robots have to complete it

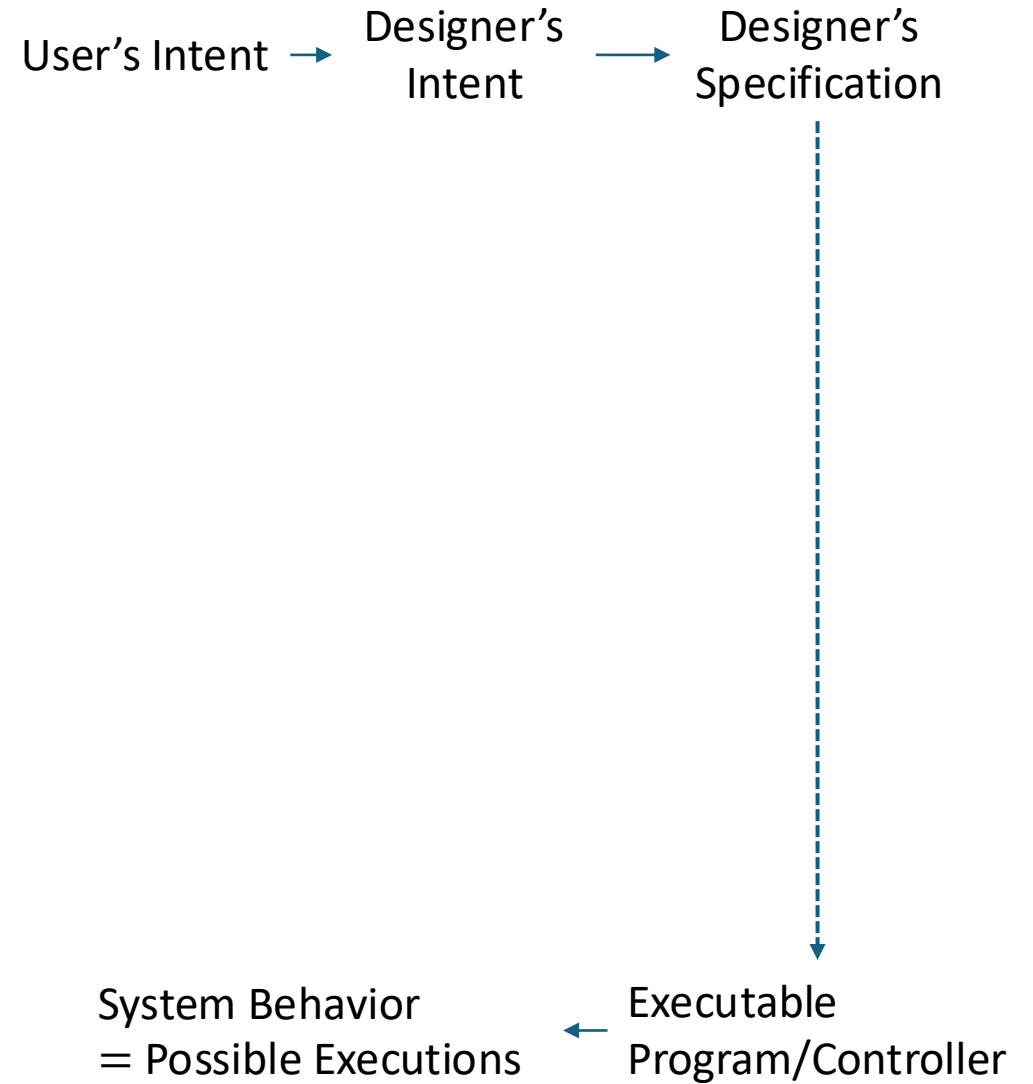
- Sequential Decision-Making Systems.
- Systems designed to be able to help user.
- User has a task in mind and expects the AI system to help in that task.

Personalized Assessment of AI Systems that can Learn and Plan

- Users would like to give AI systems multiple tasks.
 - How would users know what the AI systems can do?



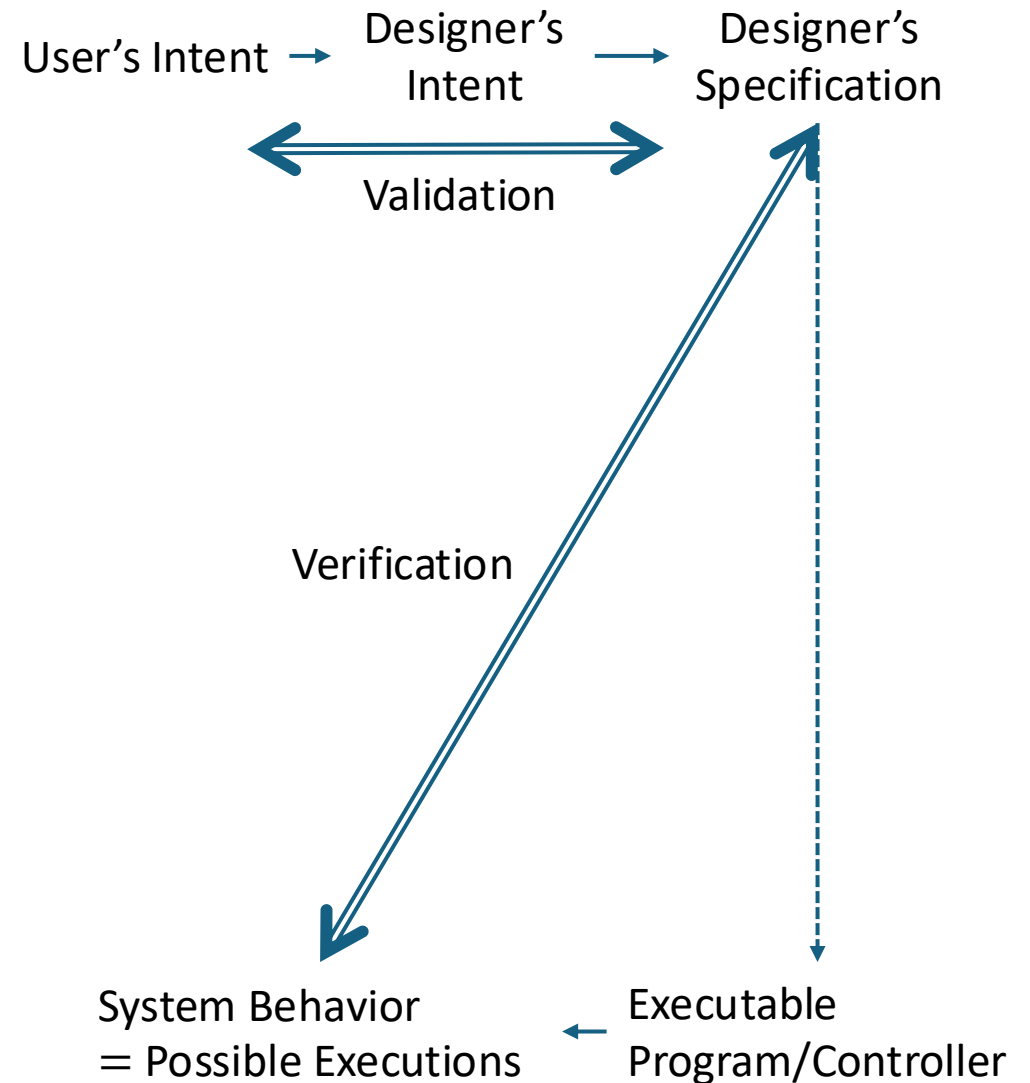
Classical Notion of Verification



Classical Notion of Verification

Input for Verification: Executable Program/Controller
(includes task spec)
+ Model/assumptions on env
+ Safety property

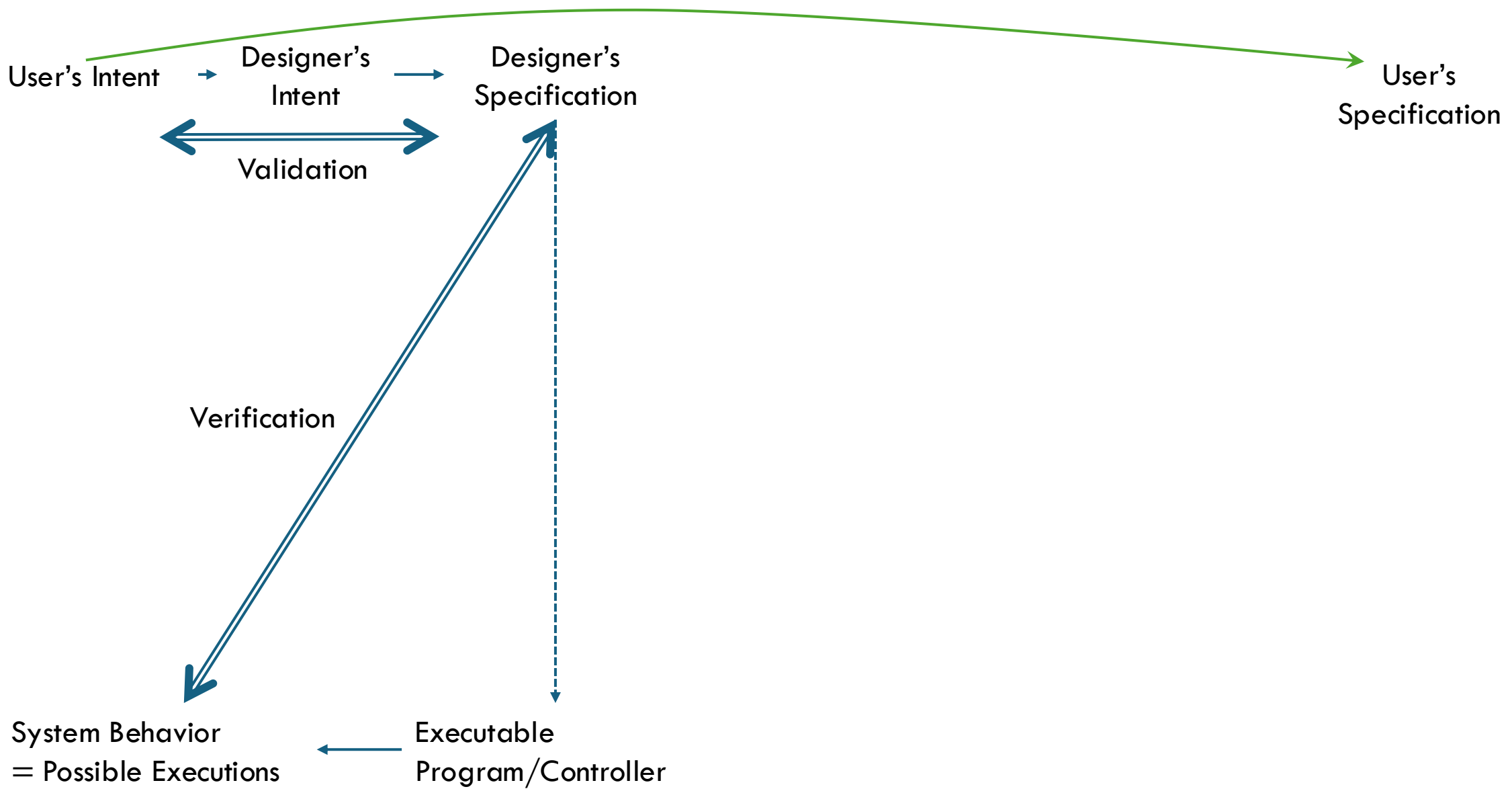
The designer plays a central role

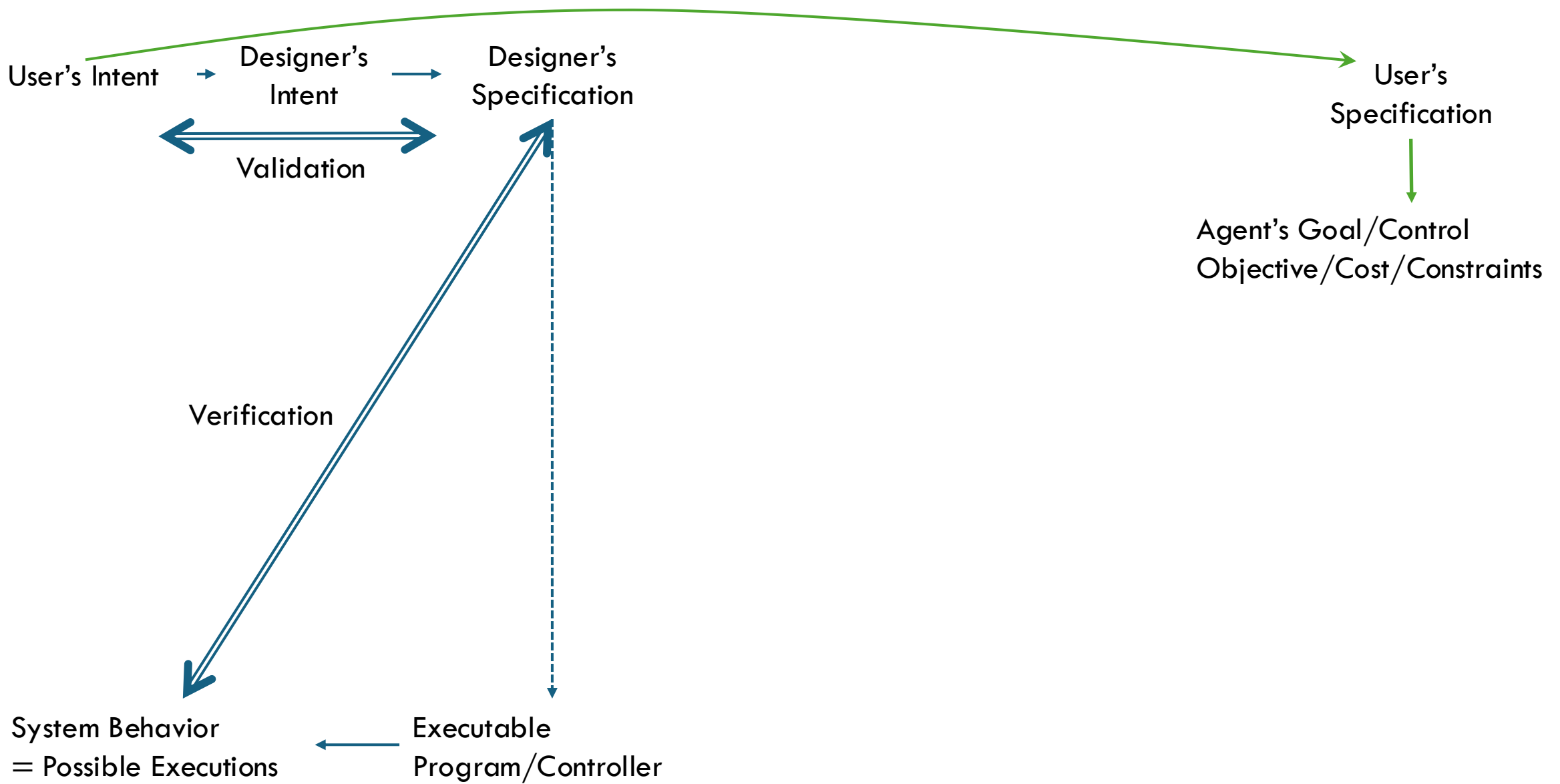


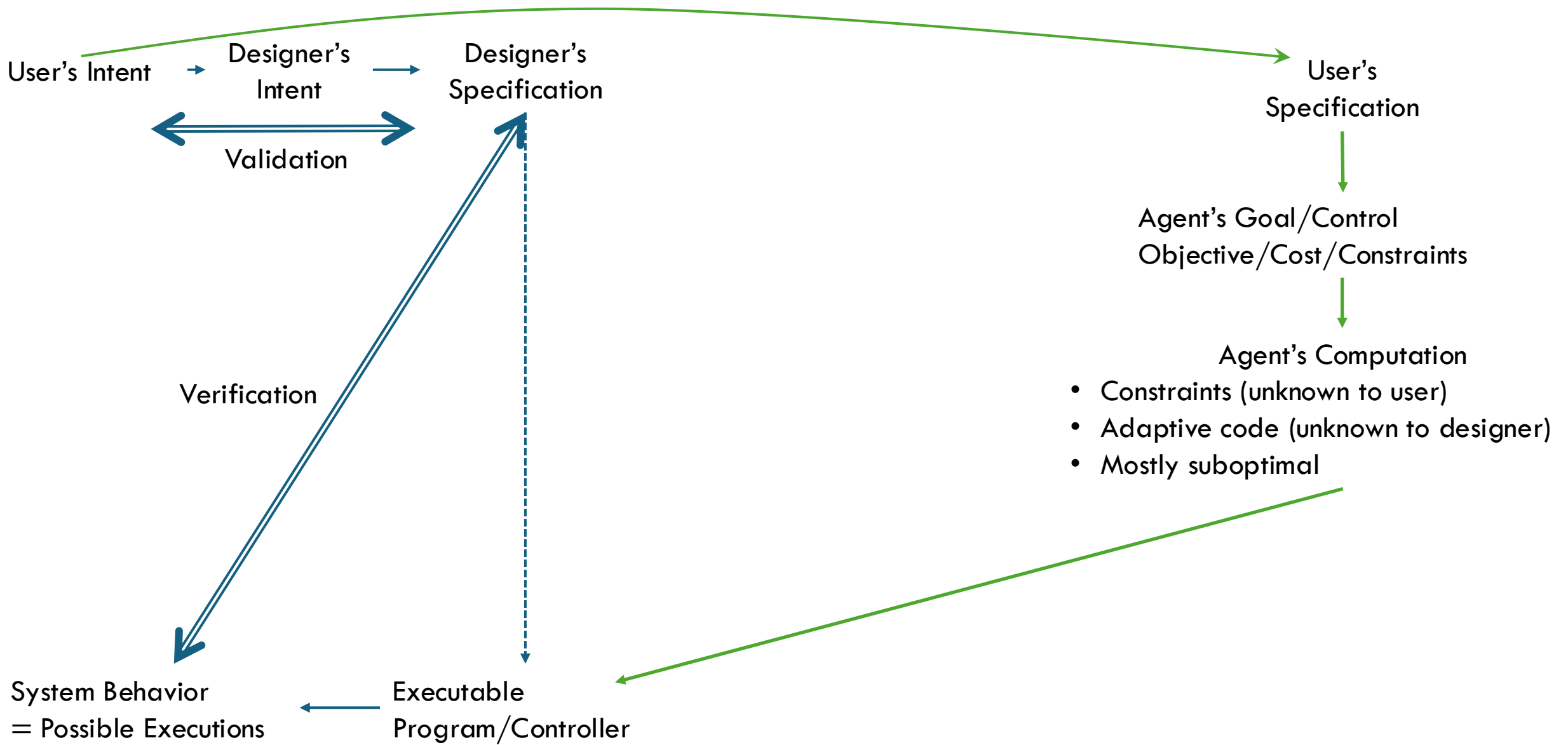
Personalized Assessment of AI Systems that can Learn and Plan

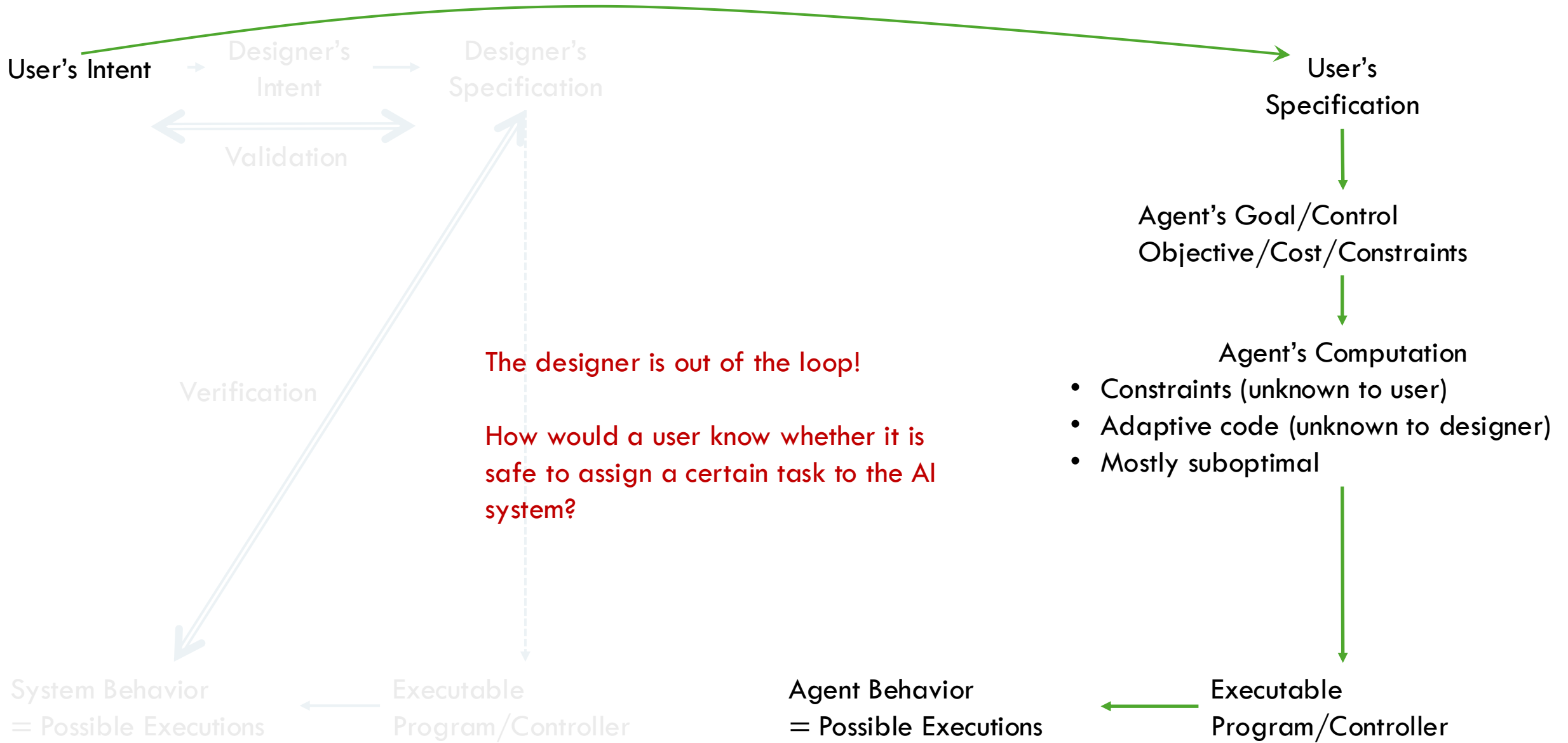
- Users would like to give AI systems multiple tasks.
 - How would users know what the AI systems can do?
- AI systems should support third-party assessment.
- The assessment should work with:
 - *Adaptive* AI systems.
 - *Black-Box* AI systems.



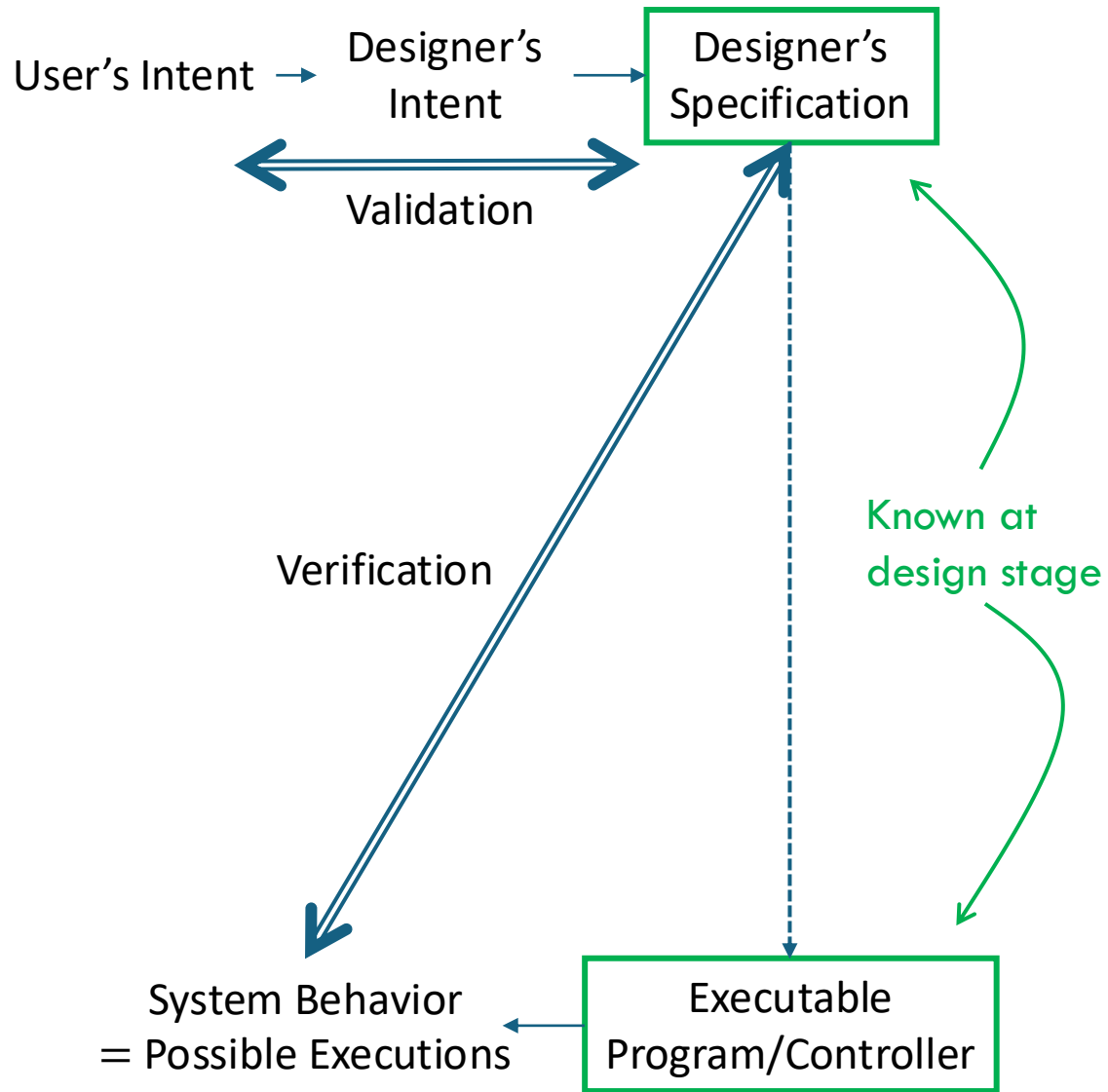




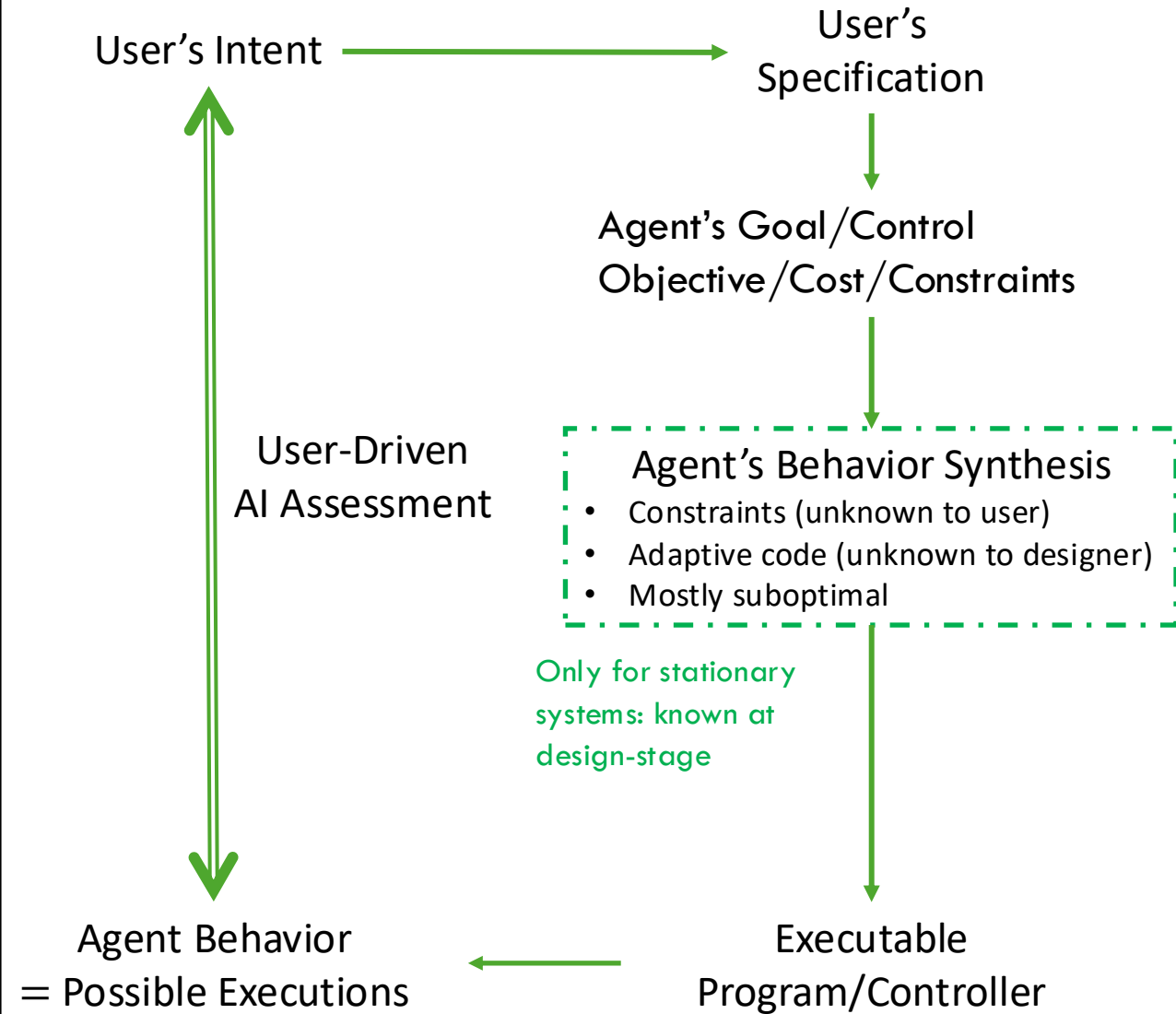




Conventional Verification



Needed for AI Systems

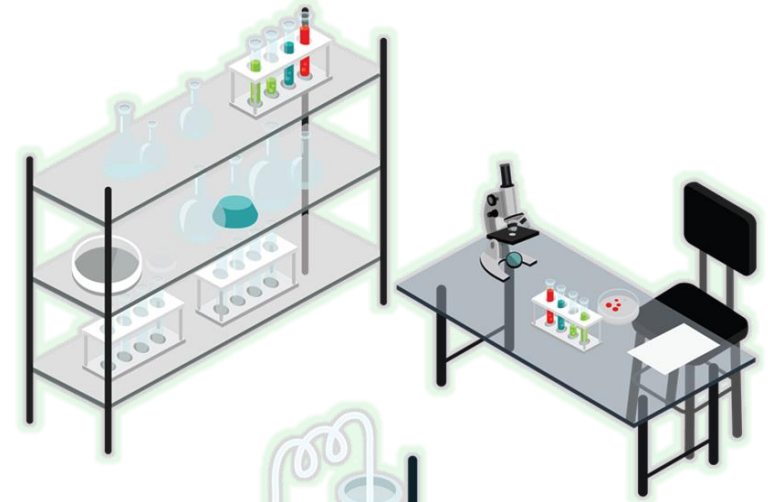


The Assessment Problem

Will it be able to safely rearrange my lab for the next round of experiments?

Output

- A description of agent's working:
 - A list of capabilities.
 - An interpretable description of each capability.



Black-Box AI

- Arbitrary internal implementation
- Comes with a Trained Policy



```
at(p0,cell_6_3)
clear(cell_0_0)
door_at(cell_9_2)
next_to(m0)
alive(m0)
key_at(9_4)
```

[Input]
Concepts that the
user understands



Personalized
AI-Assessment
Module (AAM)



Arbitrary internal
implementation

Doesn't know
user's vocabulary

Black-Box AI

```
at(p0,cell_6_3)
clear(cell_0_0)
door_at(cell_9_2)
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key_at(9_4)
```

[Input]
Concepts that the
user understands



Personalized
AI-Assessment
Module (AAM)

Query

Response



Black-Box AI



simulator

Arbitrary internal
implementation

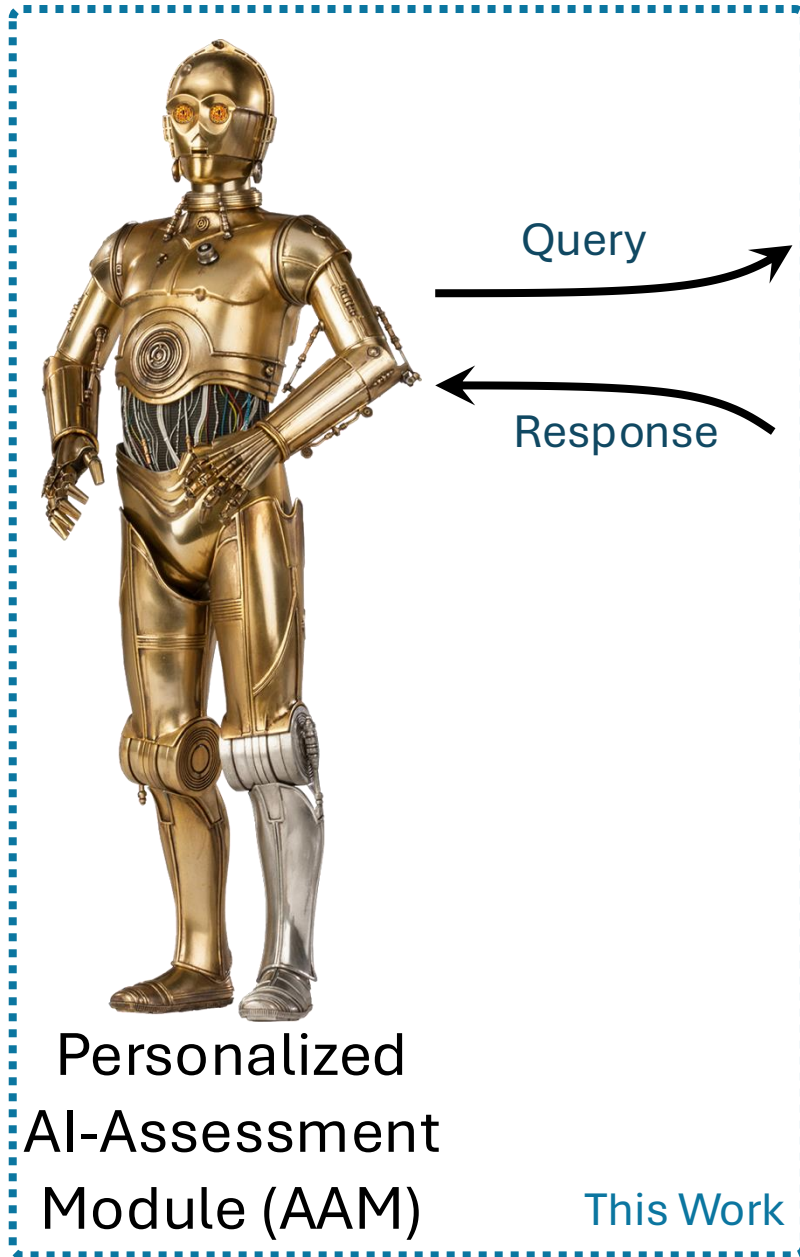
Doesn't know
user's vocabulary



[Input]
Concepts that the
user understands



[Output]
User-Interpretable
description of
Black-Box AI's
capabilities



Query



Response



simulator

Arbitrary internal
implementation

Doesn't know
user's vocabulary

Black-Box AI

The Assessment Problem

Black-Box (Taskable) AI

- Can be connected to a simulator.
- Can have arbitrary internal implementation.
- Does not know input vocabulary.

Input

- Predicates (User vocabulary)
 - With their evaluation functions

Output

- A description of agent's working:
 - A list of capabilities.
 - An interpretable description of each capability.

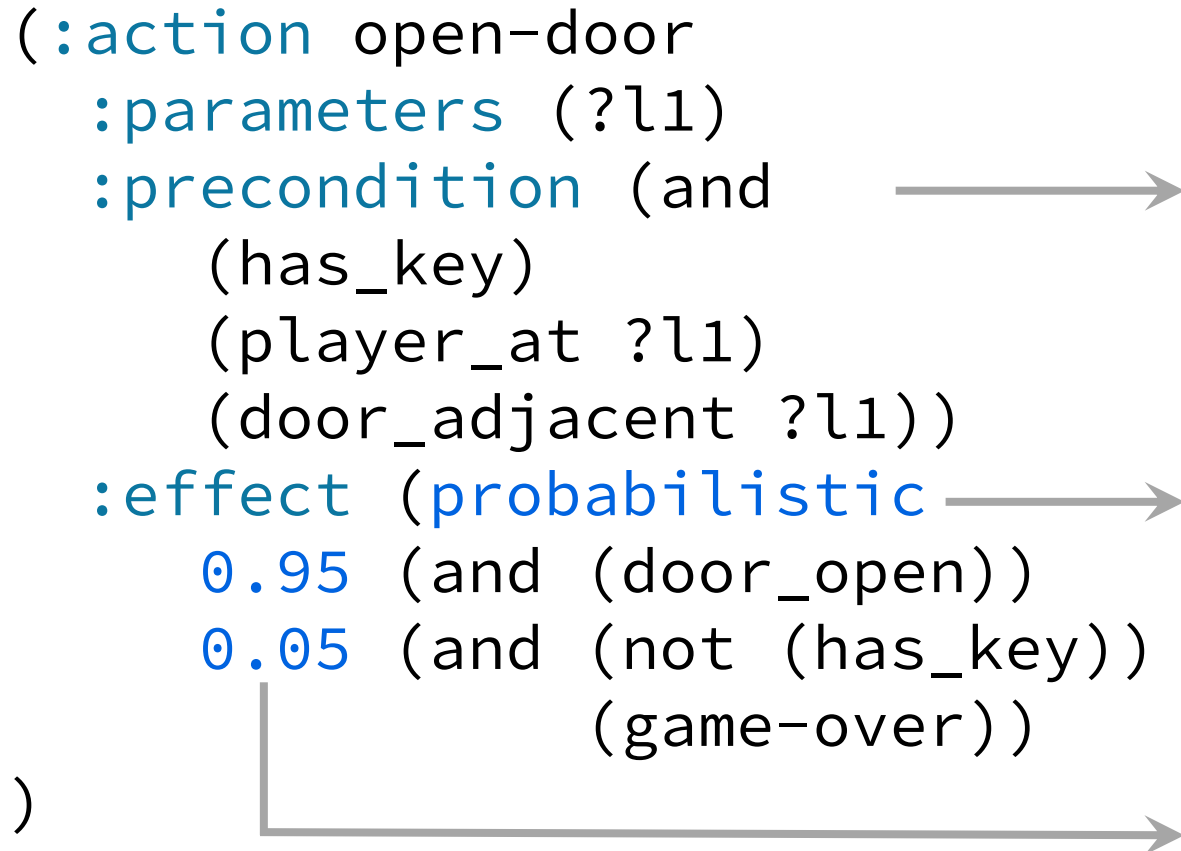


simulator

Black-Box AI

Interpretable Description: PDDL/PPDDL

```
(:action open-door
  :parameters (?l1)
  :precondition (and
    (has_key)
    (player_at ?l1)
    (door_adjacent ?l1))
  :effect (probabilistic
    0.95 (and (door_open))
    0.05 (and (not (has_key))
              (game-over)))
)
```



Precondition: This condition must be true for this action to execute

Effect: This is a set of conditions, one of which becomes true when this action is executed

Probabilities: Each set of effect has an associated probability with which that effect set is executed

Interpretable: Easily Convertible to Natural Language

```
(:action open-door
  :parameters (?l1)
  :precondition (and
    (has_key)
    (player_at ?l1)
    (door_adjacent ?l1))
  :effect (probabilistic
    0.95 (and (door_open))
    0.05 (and (not(has_key))
              (game-over))
  )
```

The player can open the door when in location ?l1 if:

- It has the key
- The player is at location ?l1
- The door is adjacent to location ?l1

After executing that capability:

- With 95% probability, the door will open
- With 5% probability, the player will not have the key and the game will be over

01

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02

Foundational
Approach

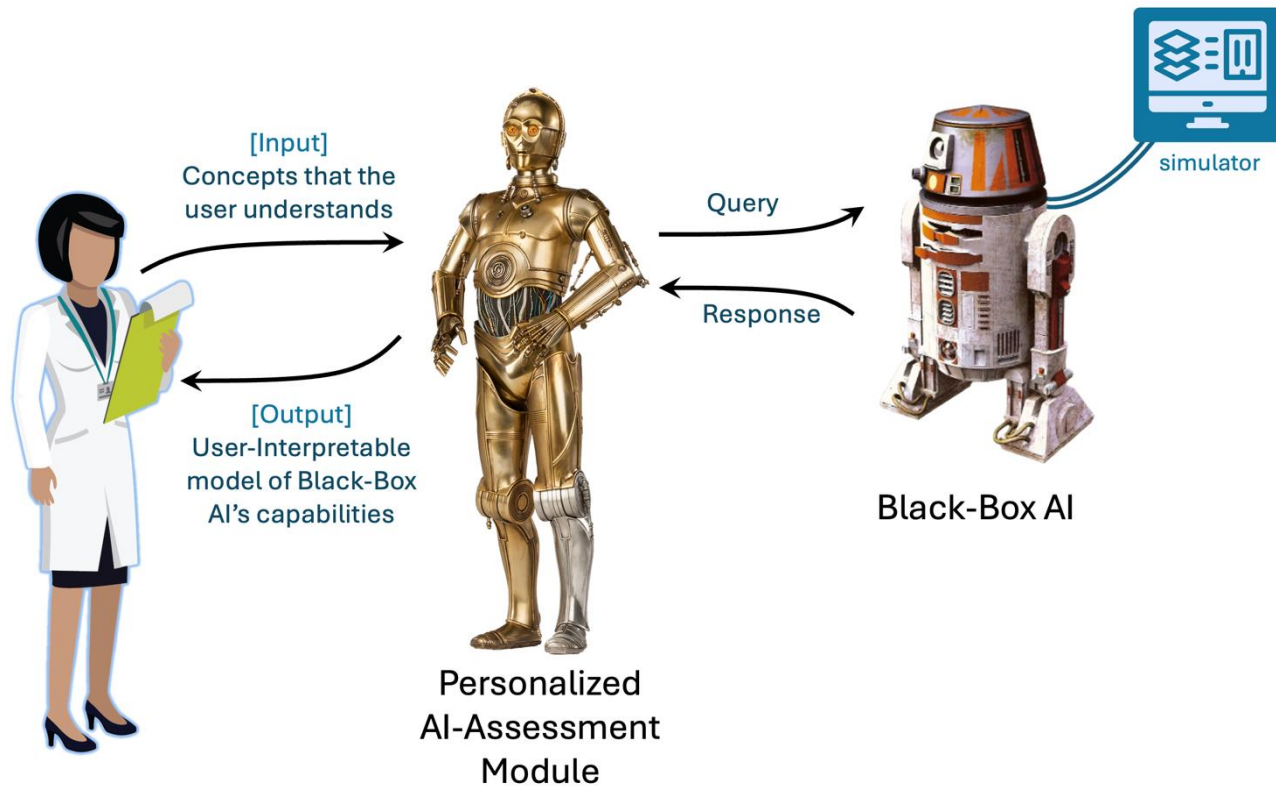
03

Generalizations

04

Future Work

Deterministic and Stationary Setting



Assumptions

- User's vocabulary matches simulator's vocabulary.
- Black-Box AI provides a list of capabilities.
- Stationary agent model.
- Deterministic environment.
- Fully observable setting.

Deterministic and Stationary Setting

Input

- Predicates (User vocabulary)
 - With their evaluation functions
- List of capabilities.



Output

- PDDL-like description of each capability.

Assumptions

- User's vocabulary matches simulator's vocabulary.
- Black-Box AI provides a list of capabilities.
- Stationary agent model.
- Deterministic environment.
- Fully observable setting.



Siddharth
Srivastava



Shashank
R Marpally

Asking the Right Questions: Learning Interpretable
Action Models Through Query Answering

Pulkit Verma, Shashank Rao Marpally, Siddharth Srivastava

In Proceedings of the Thirty-Fifth AAAI Conference on
Artificial Intelligence, 2021

Exponential Search for Learning Correct Description

- Consider the following 4 predicates/concepts:
 - (has_key)
 - (door_open)
 - (door_adjacent ?x)
 - (player_at ?x)
- Consider just one capability:
(open-door ?x)
- $9^{|C| \times |P|} = 9^{1 \times 4} = 6561$ possible models
(Assuming deterministic models/
descriptions, i.e., no probabilities).

```
(:action open-door
  :parameters (?l1)
  :precondition (and
    (+/-/∅) (has_key)
    (+/-/∅) (door_open)
    (+/-/∅) (door_adjacent ?l1)
    (+/-/∅) (player_at ?l1))
  :effect (and
    (+/-/∅) (has_key)
    (+/-/∅) (door_open)
    (+/-/∅) (door_adjacent ?l1)
    (+/-/∅) (player_at ?l1)))
```

Simple Queries

Query	In state s_I , what will happen if you execute the plan $\pi = \langle c_1, \dots, c_n \rangle$?	Can you go from state s_I to state s_F ?
Response	I can execute first ℓ steps of the plan, ending up in state s_F .	Yes / No.
	Plan Outcome Queries	State Reachability Query

- How to generate the queries?
- How to use the responses to generate models?

We have a reduction that converts this to a planning problem, so it automatically generates queries.

AAM learns Accurate Deterministic Models

- Theorem (*termination*) : The algorithm terminates after a finite number of iterations.
- Theorem (*soundness*): The resulting (set of) model(s) is(are) functionally equivalent to the ground truth model.

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04

Future Work

Stochastic and Stationary Setting

Input

- Predicates (User vocabulary)
 - With their evaluation functions
- List of capabilities.

Output

- PPDDL-like description of each capability.



Siddharth
Srivastava



Rushang
Karia

Autonomous Capability Assessment of Sequential Decision-Making Systems in Stochastic Settings

Pulkit Verma, Rushang Karia, Siddharth Srivastava

In Proceedings of the Thirty-seventh Conference on Neural Information Processing Systems,, 2023

Assumptions

- User's vocabulary matches simulator's vocabulary.
- Black-Box AI provides a list of capabilities.
- Stationary agent model.
- ~~Deterministic~~ ^{Stochastic} environment.
- Fully observable setting.

Discovering Capabilities

Input

- Predicates (User vocabulary)
 - With their evaluation functions
- Samplers: high-level state to low-level state.
- Low-level state transitions.

Output

- List of capabilities.
- PDDL-like description of each capability.



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Srivastava



Shashank
R Marpally

Discovering User-Interpretable Capabilities of Black-Box
Planning Agents

Pulkit Verma, Shashank Rao Marpally, Siddharth Srivastava

In Proceedings of 19th International Conference on Principles
of Knowledge Representation and Reasoning, 2022

Assumptions

- ~~User's vocabulary matches simulator's vocabulary.~~
- Black-Box AI provides a list of ~~capabilities.~~ *transitions.*
- Stationary agent model.
- Deterministic environment.
- Fully observable setting.

Discovering Capabilities in Stochastic Settings

Input

- Predicates (User vocabulary)
 - With their evaluation functions
- Samplers: high-level state to low-level state.
- Low-level state transitions.

Output

- List of capabilities.
- PDDL-like description of each capability.

Autonomous Assessment of Generalizability of AI Agent Capabilities

Daniel Bramblett, Rushang Karia, Adrian Ciotinga, Pulkit Verma, YooJung Choi, and Siddharth Srivastava

In ICAPS 2026 Workshop on Generalization in Planning, 2026

Assumptions

- ~~User's vocabulary matches simulator's vocabulary.~~
- Black-Box AI provides a list of ~~capabilities.~~ *transitions.*
- Stationary agent model.
- *Stochastic* ~~Deterministic~~ environment.
- Fully observable setting.

Differential Assessment

Input

- Initial model of the AI system.
 - Predicates (User vocabulary)
 - With their evaluation functions
 - List of capabilities.
- Observations collected from AI system.

Output

- Updated PDDL-like description of each capability.



Siddharth
Srivastava



Rashmeet
K Nayyar

Differential Assessment of Black-Box AI Agents

Rashmeet K Nayyar*, Pulkrit Verma*, Siddharth Srivastava

In Proceedings of Thirty-Sixth AAAI Conference on Artificial Intelligence, 2022

Assumptions

- User's vocabulary matches simulator's vocabulary.
- Black-Box AI provides a list of capabilities.
- ~~Stationary~~ ^{Adaptive} agent model.
- Deterministic environment.
- Fully observable setting.

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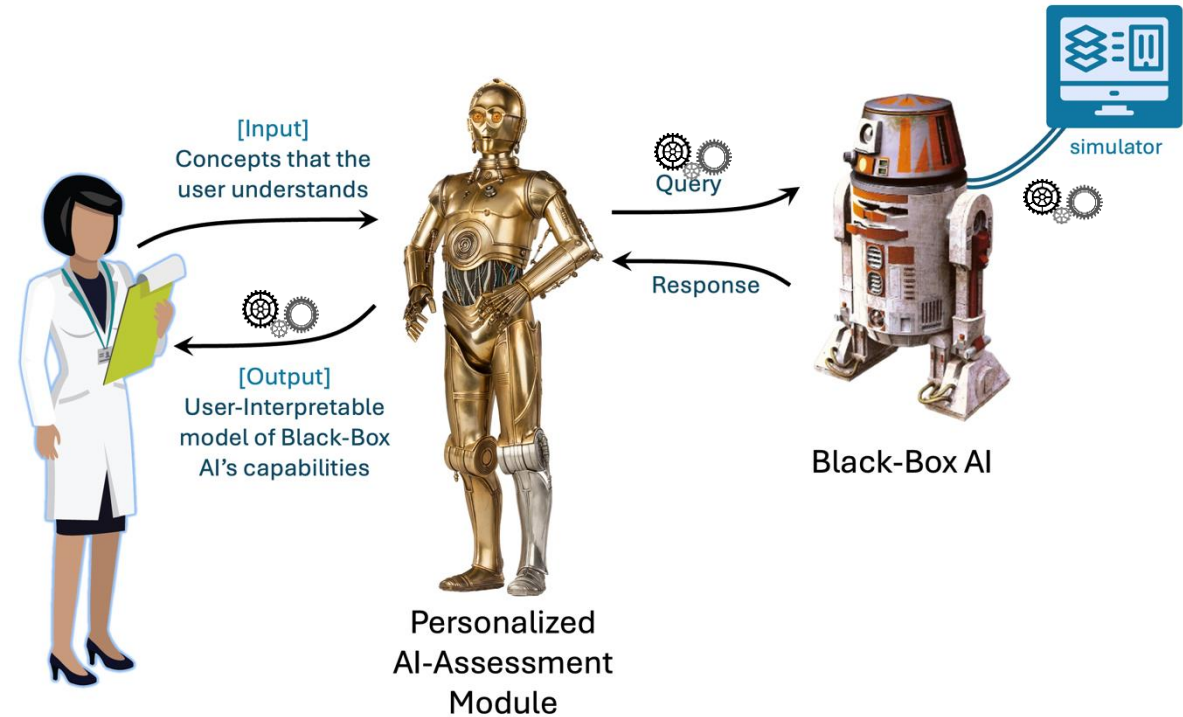
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Future Work

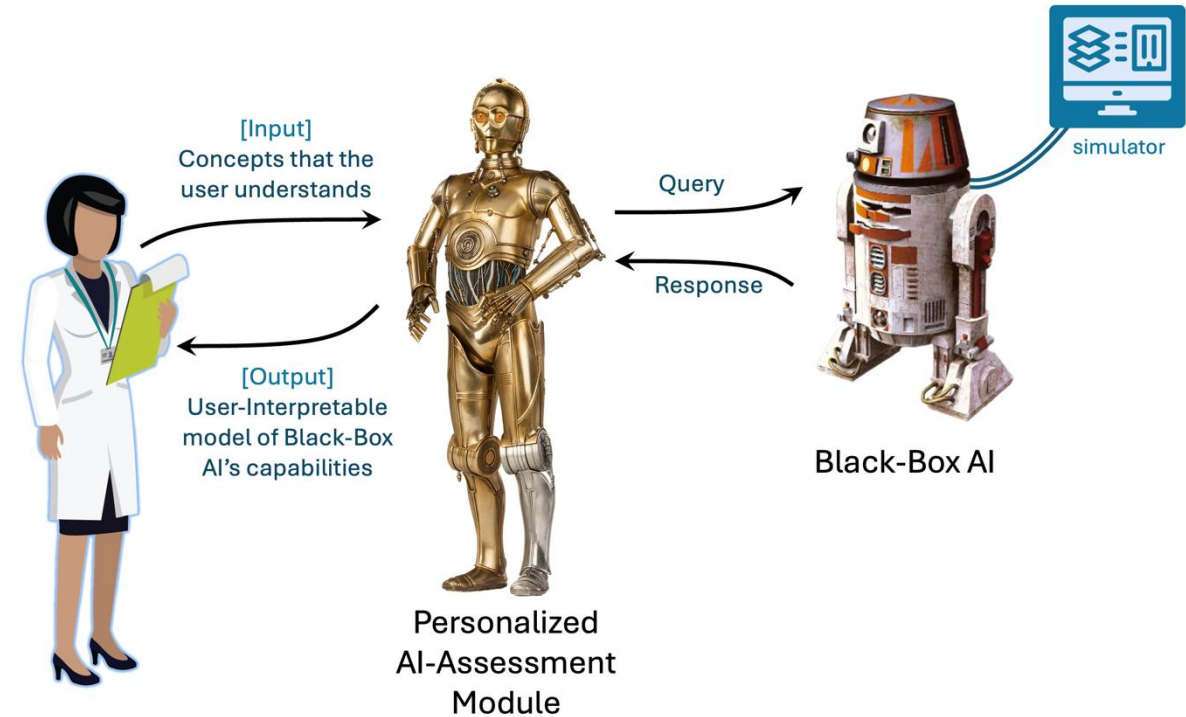
Future Work: Complexity Analysis

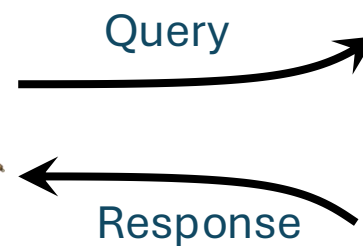
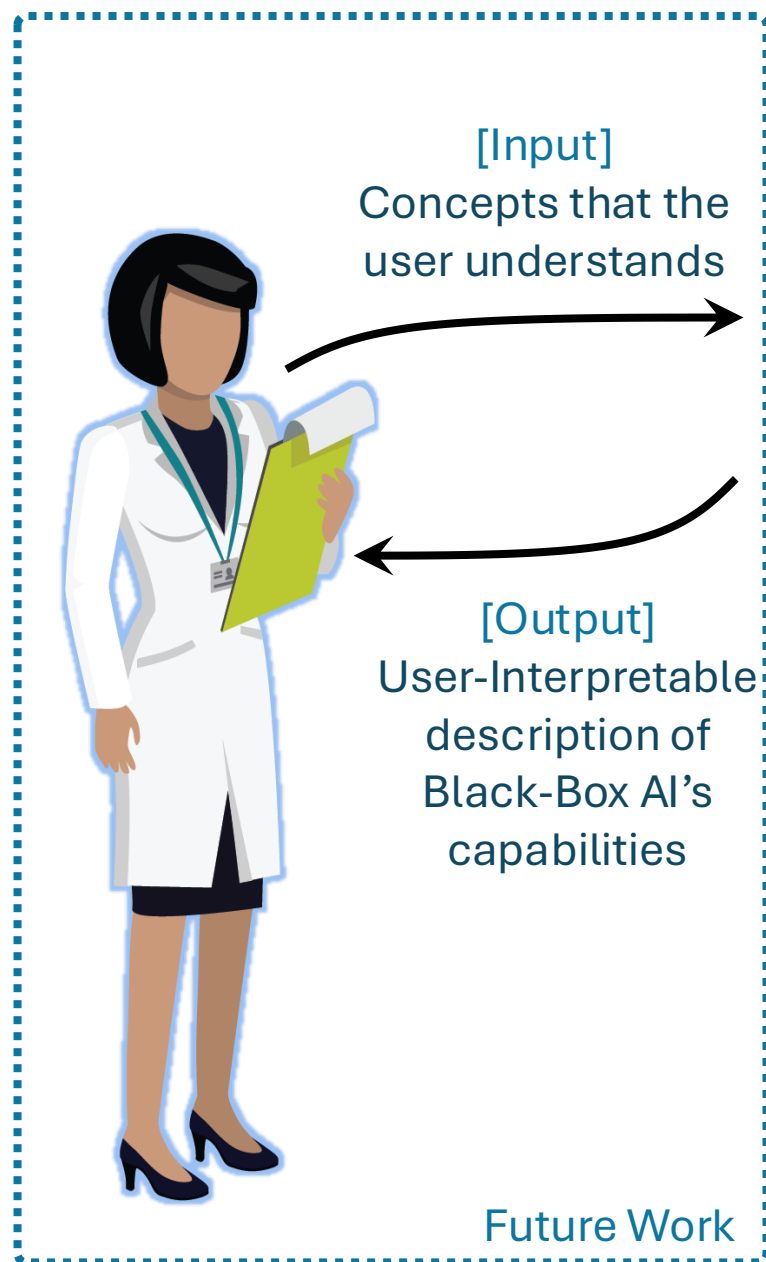
- Perform extensive analysis of queries in terms of:
 - Complexity of generating them.
 - Complexity of answering them.
 - Complexity of inferring models from Black-Box AI's responses.
- Extend the work for partially observable settings.



Future Work: Interpretable Representations

- Representations beyond PDDL.
 - LTL – Linear Temporal Logic
 - STL- Signal Temporal Logic
- How interpretable each representation is?

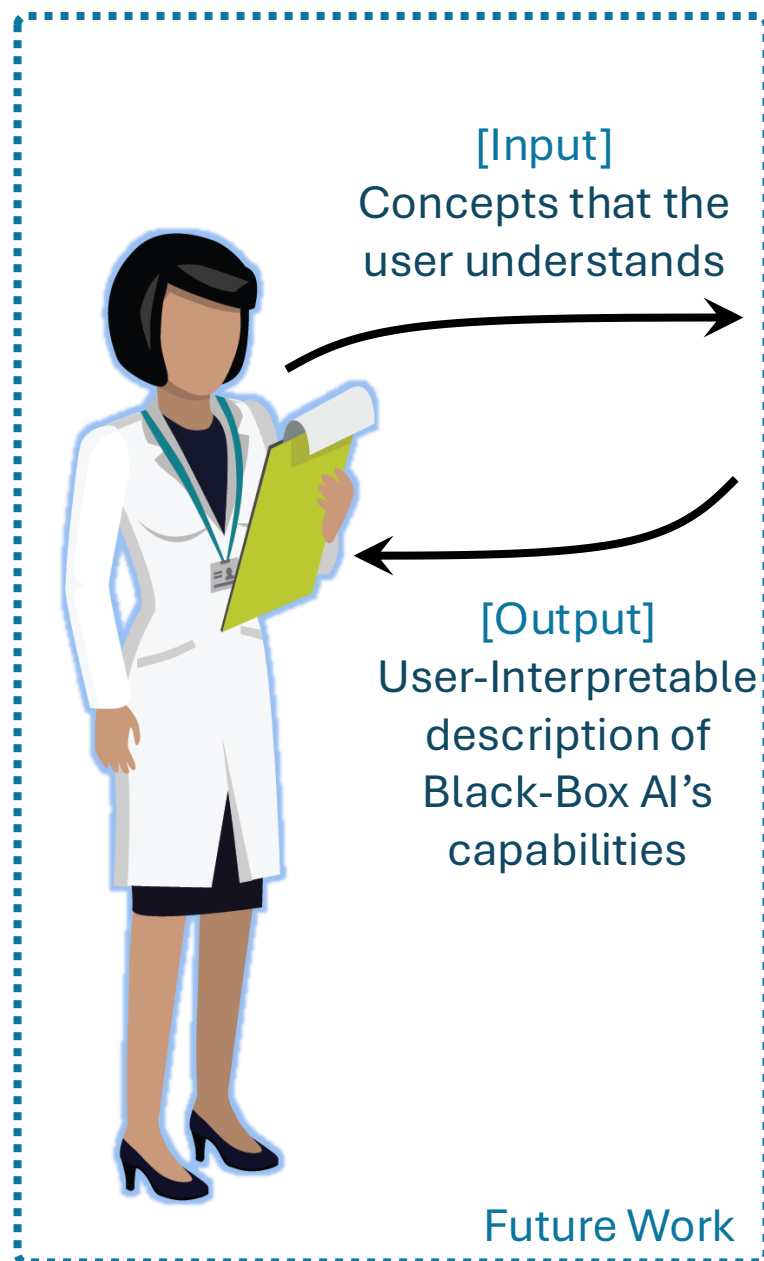




simulator

Arbitrary internal implementation

Doesn't know user's vocabulary



Personalized
AI-Assessment
Module (AAM)



Future
Work



simulator

Query

Response



Black-Box AI

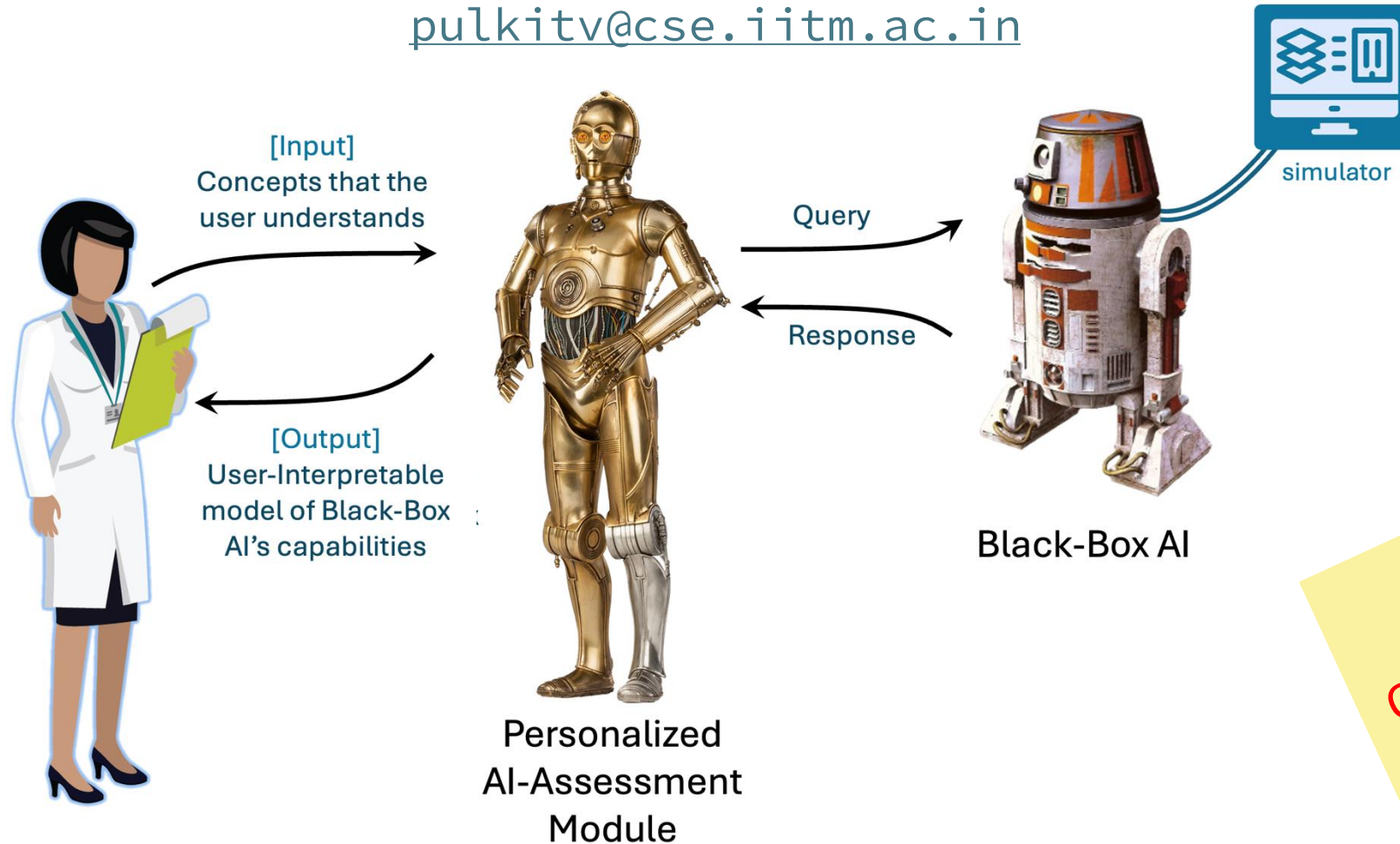
Arbitrary internal
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Questions?